# ÉTUDES ET RÉALISATIONS ÉLECTRONIQUES / INSTRUMENTATIONS / AUTOMATISME

Route de Brindas - Parc d'activité d'Arbora - N°2 69510 - Soucieu en Jarrest FRANCE

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# PROGRAMMABLE SIGNAL CONDITIONERS

# TPIv-SI 40/41

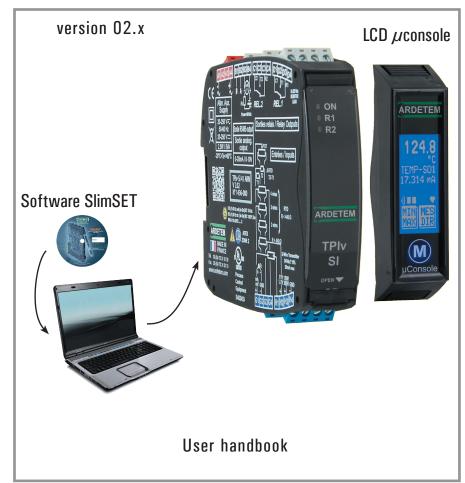


ARDETEM - TA CO/137 TPIv SI - D 07/22 Any data in this documentation may be modified without prior notice.









■ Summary	
UE conformity declaration  1. INTRODUCTION  2. SPACE REQUIREMENTS  3. CONNECTINGS  4. PROGRAMMING  Measure screen	p1 p2 p5 p5 p6 p7
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### **UE CONFORMITY DECLARATION**

The manufacturer:

ARDETEM-SFERE Route de Brindas

Parc d'activité d'Arbora n°2 69510 Soucieu en Jarrest

France

declares that the following products:

Name: Programmable signal conditioners

Type: TPIv-SI 40/41

Marking:

II 3 (1) G Ex ec nC [ia Ga] IIC T4 Gc

comply with the following directives and standards:

The Low Voltage Directive 2014/35/UE

EN61010-1:2011

The EMC Directive 2014/30/UE

EN61326-1:2013

The directive ATEX 2014/34/UE

EN 60079-0: 2012/A11:2013<sup>(\*)</sup>
EN 60079-7: 2015
EN 60079-11: 2012
EN 60079-15: 2010

IEC60079-0: 2011<sup>(\*)</sup>
IEC60079-11: 2011
IEC60079-15: 2010

ATEX/IECEx notification: QPS

Canada

UE type test certificate n°: SIRA 17 ATEX4222 X

**IECEx CofC: CSA17.0025X** 

Soucieu en Jarrest, July 20, 2022

Later Large, Jacques Huguet

Signature of the Manager

(\*) An examination of the standards EN60079-0 (2018) and IEC60079-0 (2017) does not evidence any significant changes relevant for the equipment, therefore the standards EN60079-0 (2012) and IEC60079-0 (2011) still represent the «state of the art» rules.



The instrument may be connected to dangerous electrical voltages.

It must be mounted, connected and implemented respecting the current specific regulations, by a qualified technician, trained to the safety regulations, who will have read this manual.

This appliance has to be installed in an environment defined in pollution degree 2 / Overvoltage category II or better for a max. altitude of 2000 m.

Before any installation or maintenance work, make sure the power supply of the instrument is cut.

When the instrument is permanently connected to a dangerous voltage, it is necessary to add a means of sectionalizing on the power supply (switch, fuse or circuit breaker) near to the product, to make it easy of access and to mark it as being the means for cutting the instrument.

This sectionalizing means should cut all the conductors leading the current.

Accessible parts are all communication ports (µUSB or RS485) and analog output.

The person who has designed the system (electrical installation including the instrument) is sole accountable for the safety and must make sure it has been designed according to the current safety standards.

This device is an Open Type Listed Process Control Equipment. To prevent injury resulting from accessibility to live parts the equipment must be installed in a cabinet.



This appliance contains electronic components and should not be disposed of with the domestic waste. It should be collected with the WEEE (Waste Electrical and Electronic Equipment), according to the current regulation.

### 1. INTRODUCTION

The series TPIv-SI offers intrinsic safety inputs.

They are associated equipment, to be placed in safe area or area 2 (presence of an explosive atmosphere accidentally in case of misoperation or of short duration). They are provided with input circuits for connection to a sensor located in hazardous area and output circuits for connection in safe area only or area 2.

The series TPIv offers a complete range of measure interfaces, fully programmable either with the  $\mu$ console or by PC via the configuration software and a standard USB/  $\mu$ USB cable.

The rear-lit tactile graphical LCD allows the visualisation of all the following information concerning the instrument:

- the value of the measure with its unit,
- the value of the analog output,
- the name of the product (TAG),
- the status of the relay outputs and the RS485 communications.

Scrolling message for programming help (programmable in several languages). Programming protected by code (0000 on factory exit). Programmable keys for direct access to some functions.

- Input features specific to the series TPIv-SI 41
- Thermocouple inputs (J, K, B, R, S, T, E, N, L, W, W3, WRE5)
- Sensor inputs: Pt100, Ni 100 (2, 3 or 4 wire), ∆Pt100
- Resistive sensors: caliber 0-400  $\Omega$  and 0-10  $k\Omega$
- Potentiometers: from 100  $\Omega$  to 10 k $\Omega$
- Input features common to the series TPIv-SI 40 and TPIv-SI 41
- A bidirectional DC current or voltage input:
- $\pm 100$  mV,  $\pm 1$ V,  $\pm 10$ V,  $\pm 150$ V,  $\pm 270$ V,  $\pm 20$ mA.

#### **Available options (specify on order)**

- Isolated analog output: option A:

Active or passive current, or voltage output (programmable).

### - Relay output R:

2 relays - Mode setpoint or mode window.

Recording of the alarms.

Time delay and hysteresis adjustable on each setpoint.

Alarm messages.

- Isolated digital data link N: RS 485 2 wire, protocole MODBUS-JBUS.

# **Coding**

Type	TPIv-SI XXX	X ARN		
Inputs: TPIv-SI 4		<u>o</u>		analog I/U isolated 2 change-over relays digital RS 485 isolated
			114	ulgital 110 400 130latet

### **Available versions:**

TPIv-SI 40/41	Α	AR	ARN

- CJC terminal (option): reference B1CSF-4
- Standard programming cable USB type A male to  $\mu$ USB type B male: reference C1- $\mu$ USB

# **Features of the inputs**

TPI	v-SI	Types of	Measure range		Permanent	Intrinsic	. Input
40	41	IÑPUTS	adjustal	ole from:	overload	error	impedance
•	•	mA(1)		2mA (U) 22mA(B)	±100mA		Max. drop 0.9V
•	•	mV(1)	-10 to +110mV (U) -110 to +110mV (B)		±1V	< ±0.1% of the MR for inputs of the	
•	•	V	-0.1 to +1.1V (U) -1.1 à +1.1V (B) -1 to +11V (U)		±50V	type (U)  < ±0.05% of the MR for	
			-11 to +	11V (B)		inputs of the type (B)	≥ 1MΩ
			-165 to +	165V (U) 165V (B) 300V (U)	±300V		
	•	Thermocouples(1) Standard IEC 581 J K B R S T E N L W W3 WRE5	°C -160/1200 -270/1370 200/1820 -50/1770 -50/1770 -270/410 -120/1000 0/1300 -150/910 1000/2300 0/2480 0/2300	°F -256/2192 -454/2498 392/3308 -58/3218 -58/3218 -454/770 -184/1832 -32/2372 -238/1670 1832/4172 32/4496 32/4172	-	<±0.1% of the MR or 30µV typical (60µV max.)	≥1 MΩ
	•	Pt100Ω sensor (1)(2) Standard IEC 751 (DIN 43760)	°C -200/850	°F -328/1562	-		
	•	Ni 100 sensor (1)(2)	-60/260	-76/500	-	<±0.1% of the MR	Current
	•	Differential measures from 2 sensors Pt100Ω 2 wire Standard IEC 751 (1)	-200/270	-328/518	-	OI THE IMIT	250μΑ
	•	Resistive sensors	and 0-10 kΩ (1) <±0.1%			Max. current 250µA	
	•	Potentiometer	from 1000	of the MR $\sim$ 100 $\Omega$ to 10 k $\Omega$		OI UIG IVIIX	Max. voltage 100mV
•	•	Supply for 2-wire sensor	271	7 Vdc / 020	mA with protecti	on from short-ci	rcuits : 25 mA.
•	•	Special linearisation programming up to 20 points	On input: mV, V, mA. resistive sensor and potentiometer			er	
•	•	Extraction of the square root	On input mV, V or mA				

- (1) Sensor break detection: mA input (if down scale ≥ 3.5mA) Other inputs: A 12µA pulsed current allows the detection of line or sensor break.
- (2) Wiring in 2, 3 and 4 wire possible The influence of the line resistance (0<Rl<<25 $\Omega$ ) is included in the announced intrinsic error.
- (3) Efficiency of the CJC (-20°C to 60°C):

Internal CJC: ±2°C ±0.03°C/°C CJC (option terminal): ±1°C

MR Measure range Thermal drift <150ppm /°C

/්ර	Types of OUTPUTS		Features
		Current	Current: Direct or reversed 0-20mA Load impedance ≤ Lr 600Ω
Α	active/passive  1 analog  Voltage		Voltage: Direct or reversed 0-10V Load impedance: ≥ Lr 5KO
			Accuracy: 0.1% in relation to the display
			Ripple: 0.2%
			Response time in relation to the display: 40ms.
R	2 change-over relays		2 setpoints per relay configurable over the whole MR. Hysteresis programmable from 0 to 100%. Time delay programmable from 0 to 999,9 sec. (5A/250 VAC on resistive load)
N	Digital data link RS485 Protocole Modbus/Jbus (EIA RS485) isolated.		

#### Response time

(for a variation from 10 to 90% of the input signal)

Average response time 150 ms

(1) Add 40 ms for the response time on the analog output, or 10 ms for the response time on the relay outputs.

# **General features**

#### Galvanic isolation:

3.8kV-50Hz-1min. between input and [supply/outputs]

3.0kV-50Hz-1min. between relay outputs and [analog output/RS485 output/supply]

3,0kV-50Hz-1min. between relay output 1 and relay output 2 1.0 kV-50Hz-1min. between analog output and RS485 output

Working voltage: 250 Vac/dc

PARAMETRES ELECTRIQUES RELATIFS A LA SECURITE SAFETY ELECTRICAL PARAMETERS						
Type de mesure Measure type	Câblage Wiring	Uo (V)	lo mA	Po (mW)	Co (µF)	Lo (mH)
Alimentation capteur 2-wire sensor supply	G1-H1	28.4	90.5	643	0.077	4
mV, V, mA, Tc, RTD Résistance, potentiomètre Resistance, potentiometer	G1-G2-G3 G4-H2 H3-H4	8.0	2.0	2.0	8.4	>1000
Um < 2	Um < 250 Vdc and Um < 250 Vac					

#### Power supply:

Max. operating range	Power draw	Dielectric withstanding
20-250 Vac & 20-250 Vdc	2.5 W max. 5 VA max.	3.0KV-50Hz-1min.

#### Measure:

Standard sampling time: 100 ms
Common mode rejection rate: 130 dB
Serial mode rejection rate: 70 dB 50/60 Hz

Self-calibration

#### Use:

Operating temperature: -20 to 60°C
Storage temperature: -20 to 70°C

• Use in pollution degree 2 and voltage surge category II or better

• Max. altitude: 2000m

# Compliance with standards:

Directive LV 2014/35/UE	EN 61010-1
Standard for UL electrical safety	UL 61010-1
	CSA C22.2 NO.61010-1-12
Directive ATEX 2014/34/UE	EN 60079-0, EN60079-7
	EN 60079-11, EN60079-15
IECEx	IEC 60079-0, IEC 60079-7
	IEC 60079-11, IEC 60079-15
Directive EMC 2014/30/UE	EN 61326-1

# Marking:









Process Control Equipment E482453

#### Housing:

- Self-extinguishing case of black UL 94VO PA66
- · Mounting in switchbox: latching on symmetrical DIN rail.
- Removable terminal blocks for screwed connections (2.5mm², flexible or rigid)
- Screw thread M3

Max. tightnening torque: 0.5Nm / 4.5in.lbs

Min. solid/stranded conductor section: 0.2mm2 / 26A WG Max. solid/stranded conductor section: 2.5mm2 / 14A WG

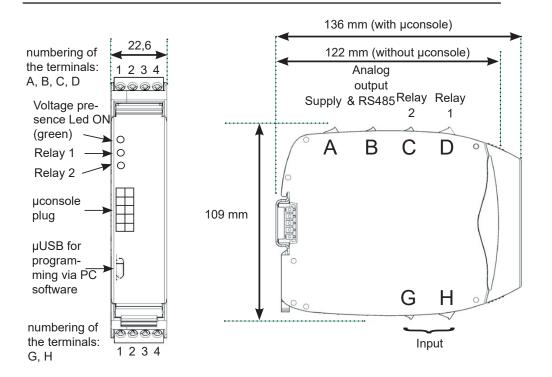
• Protection: case / terminals: IP20

**Dimensions:** without µconsole: 109mm x 122mm

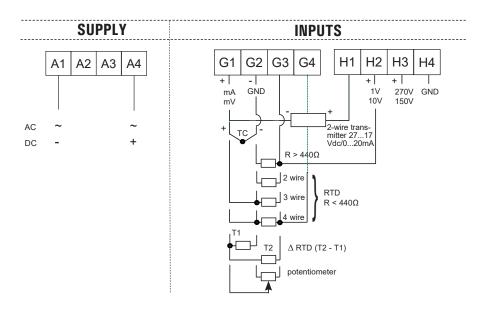
with µconsole: 109mm x 136 mm

Max. weight: 290g (with packaging)

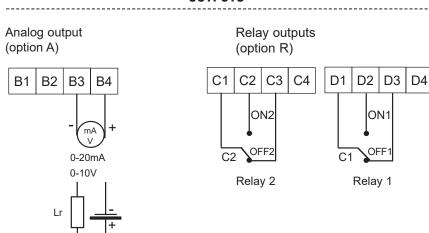
# 2. DIMENSIONS



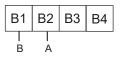
# 3. CONNECTINGS



#### OUTPUTS



RS485 output (option N)



Vmax = 30Vdc

# INSTALLATION IN AREA 2 (ATEX and IECEx):

The product must be installed by qualified staff, competent on the directives and the regulation applicable to the area 2.

In locations where high external humidity and internal temperature variations (e.g. frequent on-off cycles) may cause condensation inside the equipment, the interior should be periodically inspected.

When installed in the hazardous or non-hazardous area, the equipment shall be installed in a suitably-certified enclosure (Ex ec for gas applications Zone 2). When installed in a non-hazardous area, the equipment may alternatively be installed in a controlled environment that proivdes equivalent protection. The installer shall ensure that the maximum ambient temperature of the equipment when installed is not exceeded.

Cable entries and blanking elements shall fullfil the same requirements.

When the device is mounted in an hazardous area, connection and disconnection of the module connectors while live is only permitted if the potentially explosive atmosphere is shown to be absent.

The field installation shall be undertaken in a controlled environment with suitably reduced pollution, limited to pollution degree 2 or better as stated in manufacturer's documentation.

The non-intrinsically safe circuits may only be connected to an overvoltage category I or II power source, as defined in IEC 60664-1.

The supply shall be protected such that transients are limited to a maximum of 140% of the rated voltage; no such protection is required for the signal lines.

# 4. PROGRAMMING

#### With the micro-console

 $(LxhxD = 23.3 \times 89.5 \times 24.3 mm)$ 

This  $\mu$ console for clipping on the front face allows the visualisation of the measure or occasional modifications of the programming via its tactile keyboard. It also allows the teleloading of a programming file to other products of the ARDETEM range.

The programming menus and the functions which can be accessed from the console are detailed in the following pages.

The graphical rear-lit LCD allows the visualisation of 3 pieces of information:

- the value of the measure (5 mm high) with its unit,
- the value of the analog output and the name of the product (TAG),
- the status of the relay outputs and the RS485 communications.
- Scrolling message for programming help (programmable in several languages)
- Protection of the programming by code.
- · Programmable keys for direct access.

# Via the configuration sofware SlimSET

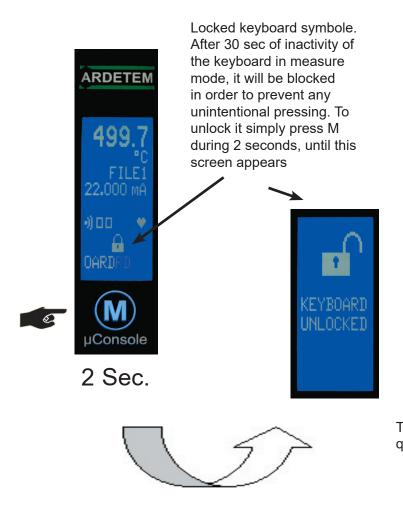
To communicate with the series TPIv-SI from a PC you will need a connection cable (USB /  $\mu$ USB standard). To connect this cable to the TPIv-SI, unclip the front face and insert the  $\mu$ USB plug into the especially foreseen USB connector. Then connect the USB plug on a USB port of the PC.

The software SlimSET allows the reading of the measures or the modification of the converter configuration.

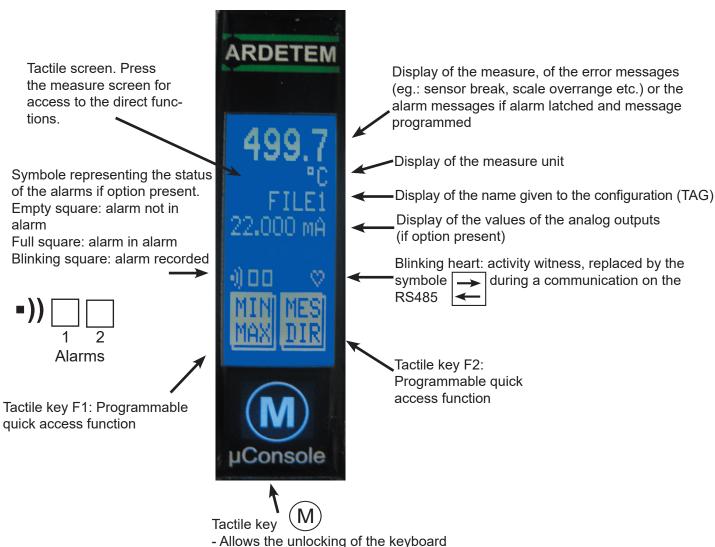
Each configuration is kept as a file stored on disk. These files can be consulted, modified, duplicated or loaded into the converters. The files can be created with or without having a converter connected. This software also allows the saving of existing configurations from the instruments already in service. All the files can be edited on any type of printer.

# Measure screen

# Unlocking of the keyboard



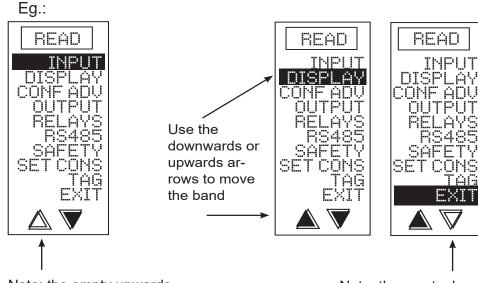
# Description



- The access to the main menu if pressed during the measure screen
- The switching back to the previous menu during the reading or the programming

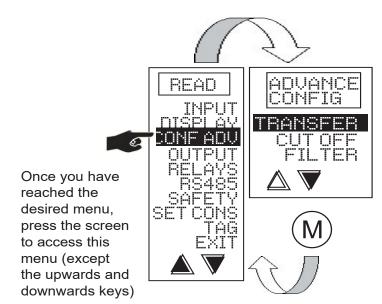
# **Moving through the list menus:**





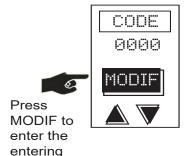
Note: the empty upwards arrow indicates that you are at the top of the menu

Note: the empty downwards arrow indicates that you are at the bottom of the menu

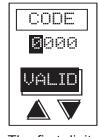


You will then enter the chosen menu. Press M to come back to the previous menu.

# Entering of a value:



mode



The first digit starts to blink. Enter the value of the first digit using the arrows.



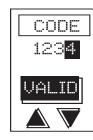
Once you have reached the desired value, press VALID to switch to the second digit.

DS INP

+100.0



Start again for the second digit and the third etc... until the last digit.



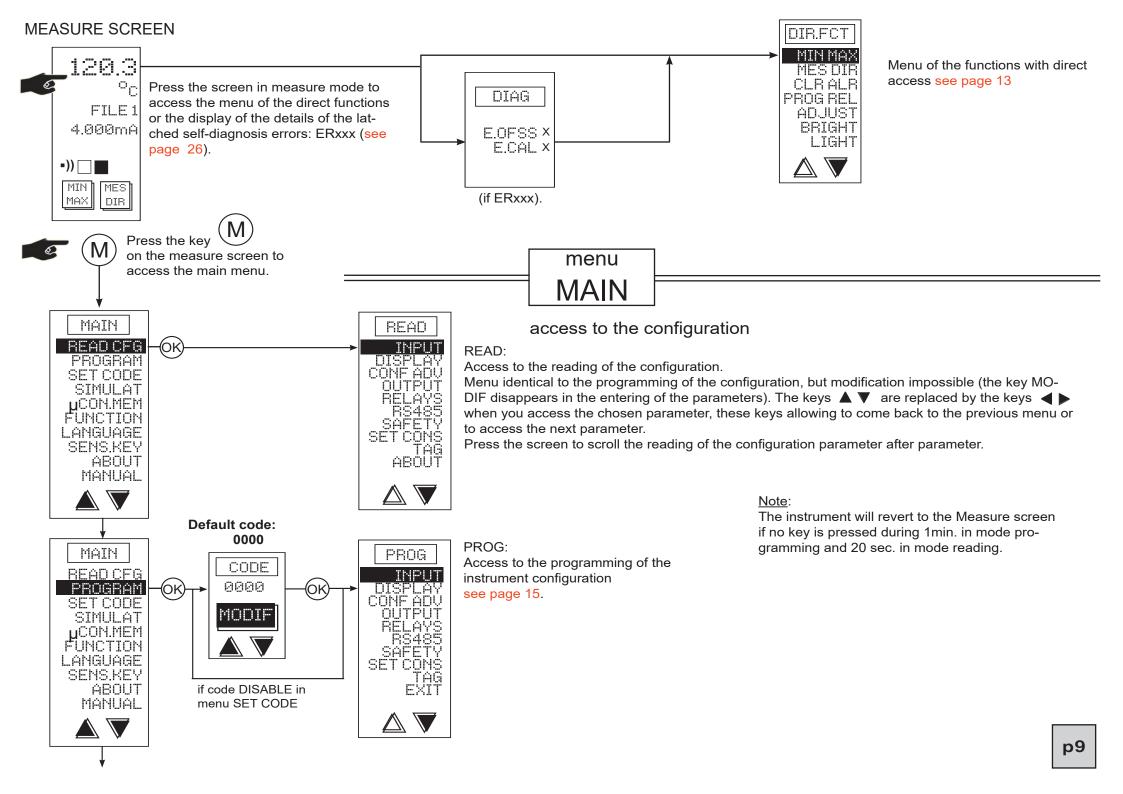
For a signed value, the entering begins by the choice of the sign.

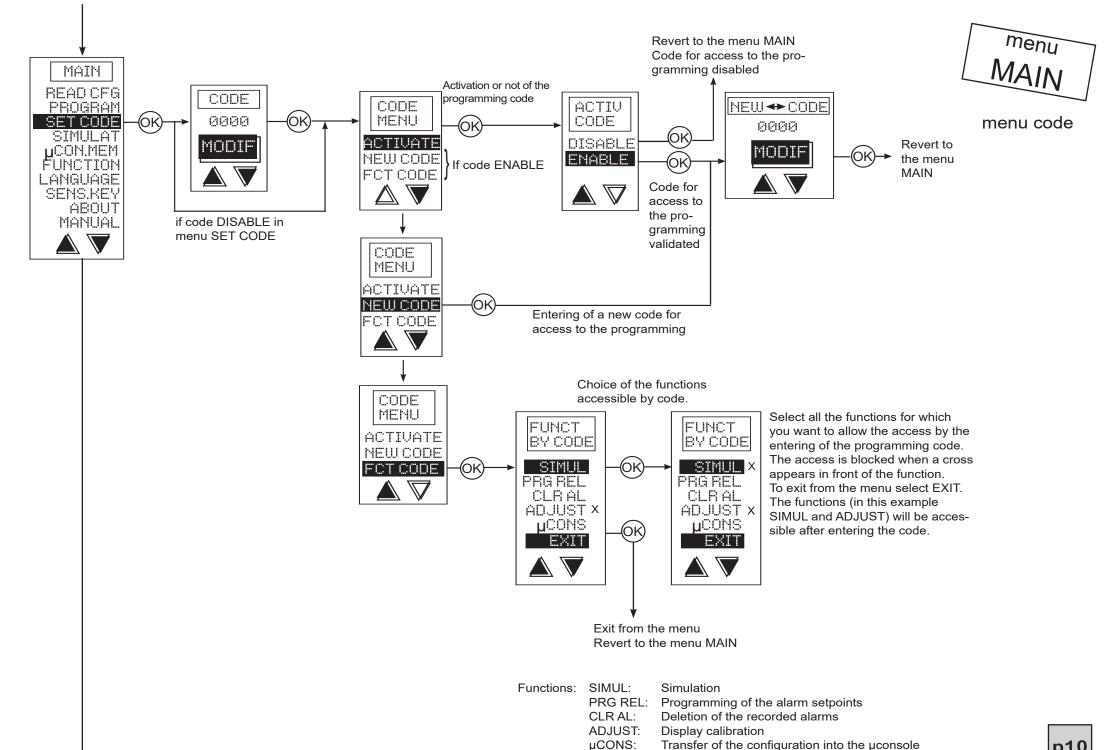


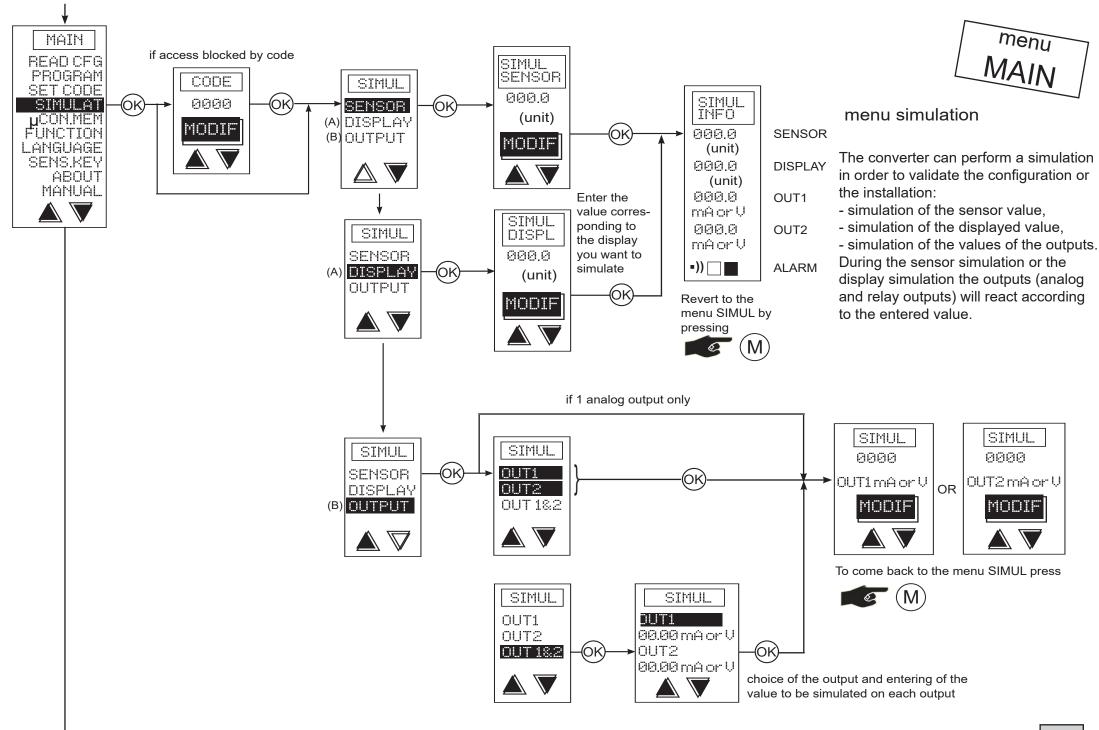
DS INP 10 00 JALID

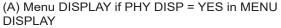
For a value with decimals the entering ends by the choice of the decimal point position, which you can move using the arrows.

Press M during the entering to revert to the former value.

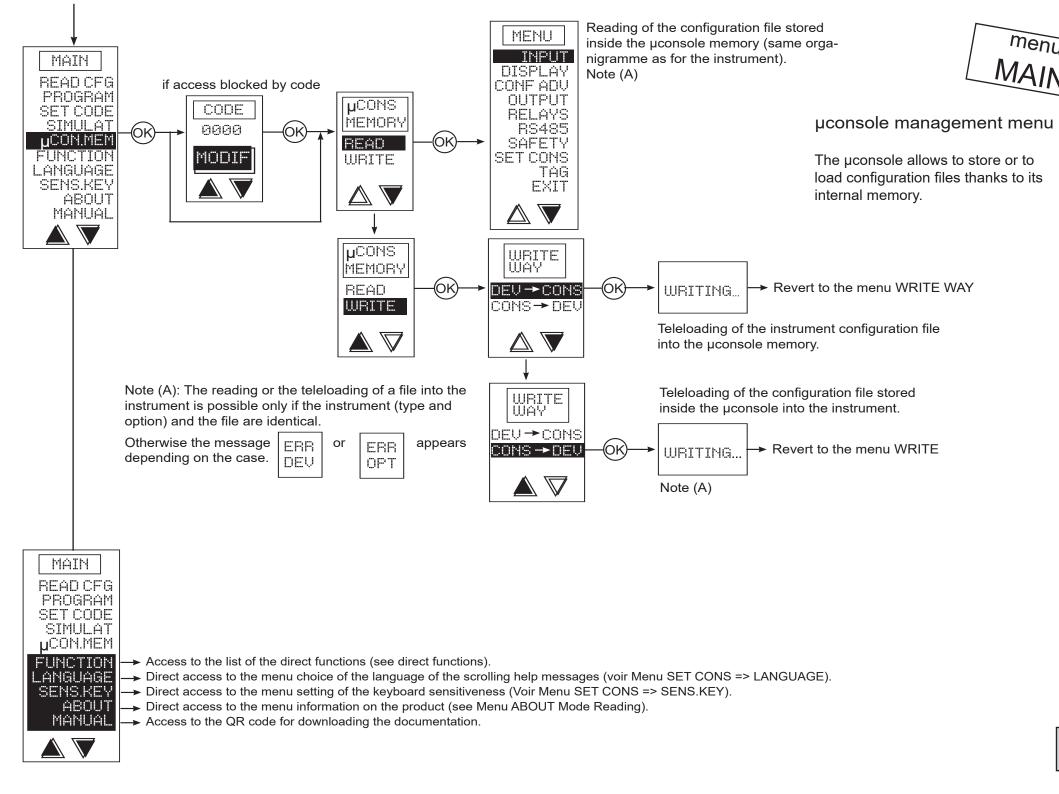


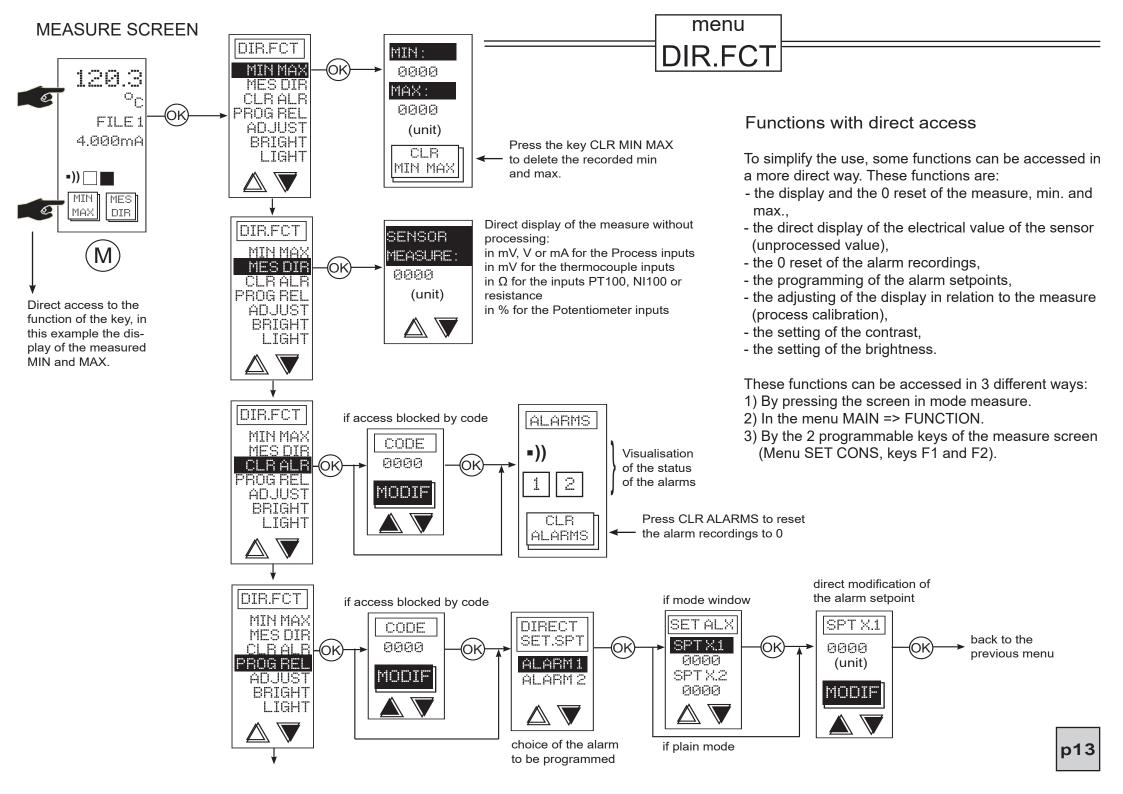


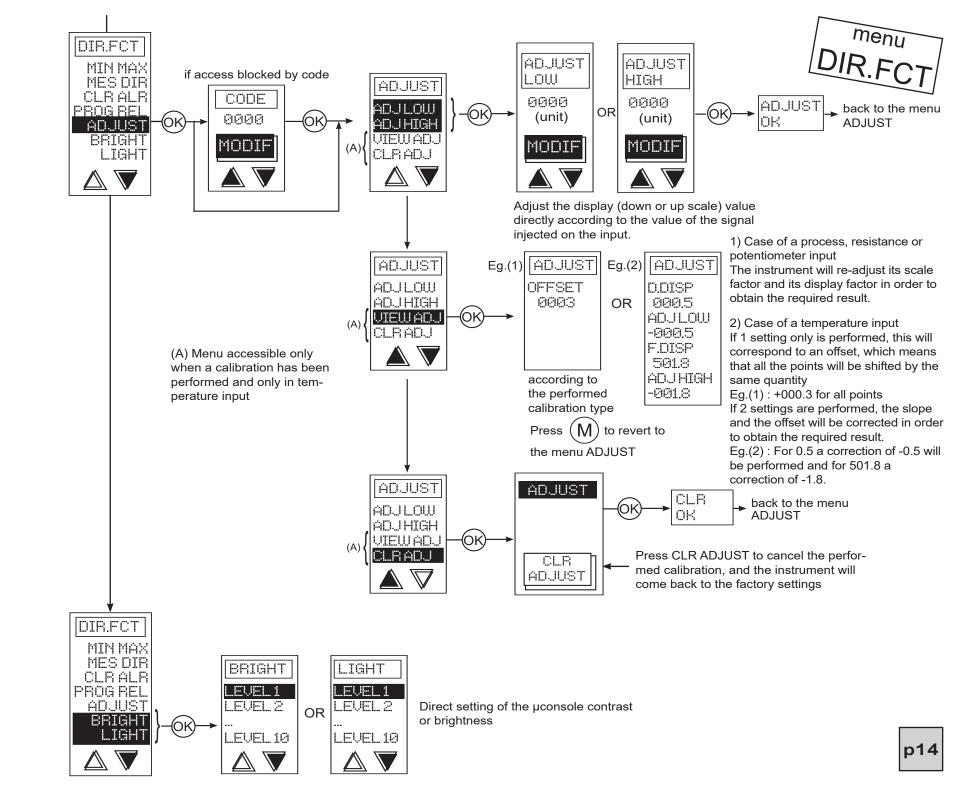


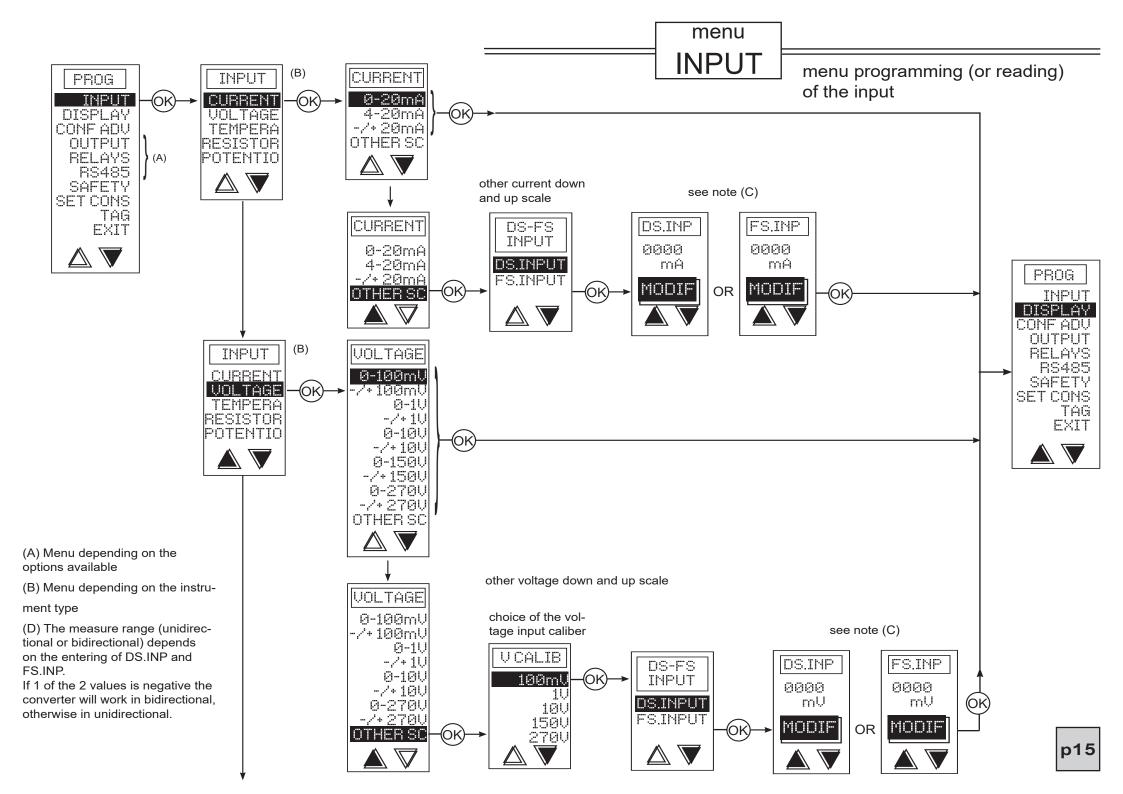


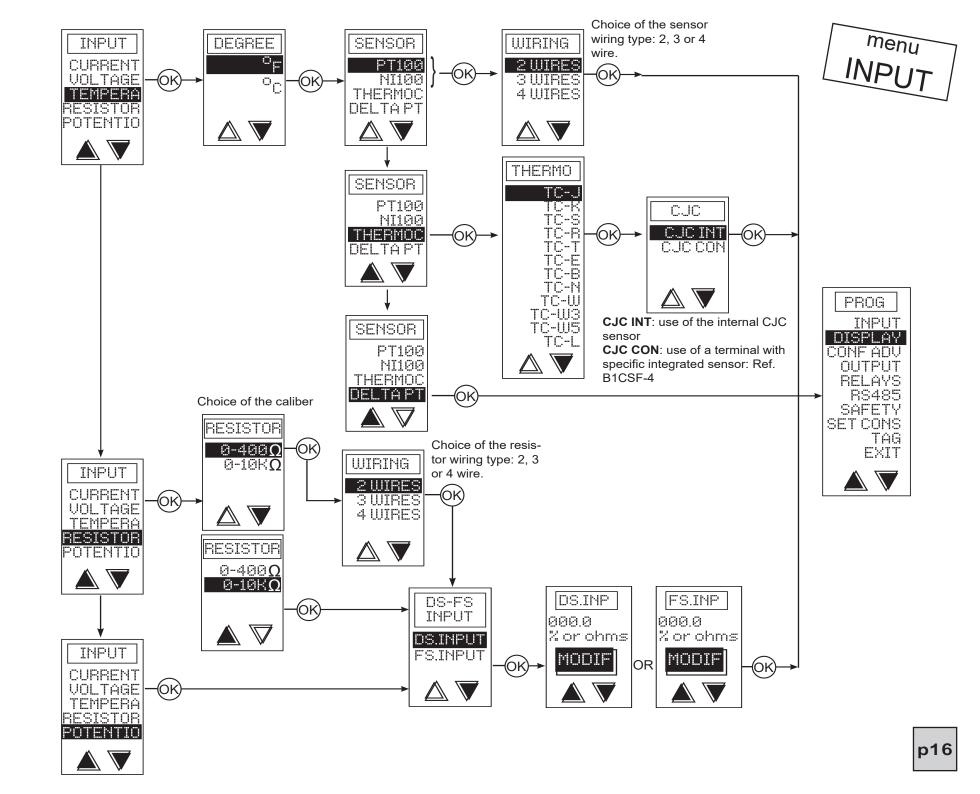
(B) Menu OUTPUT if option analog output(s)

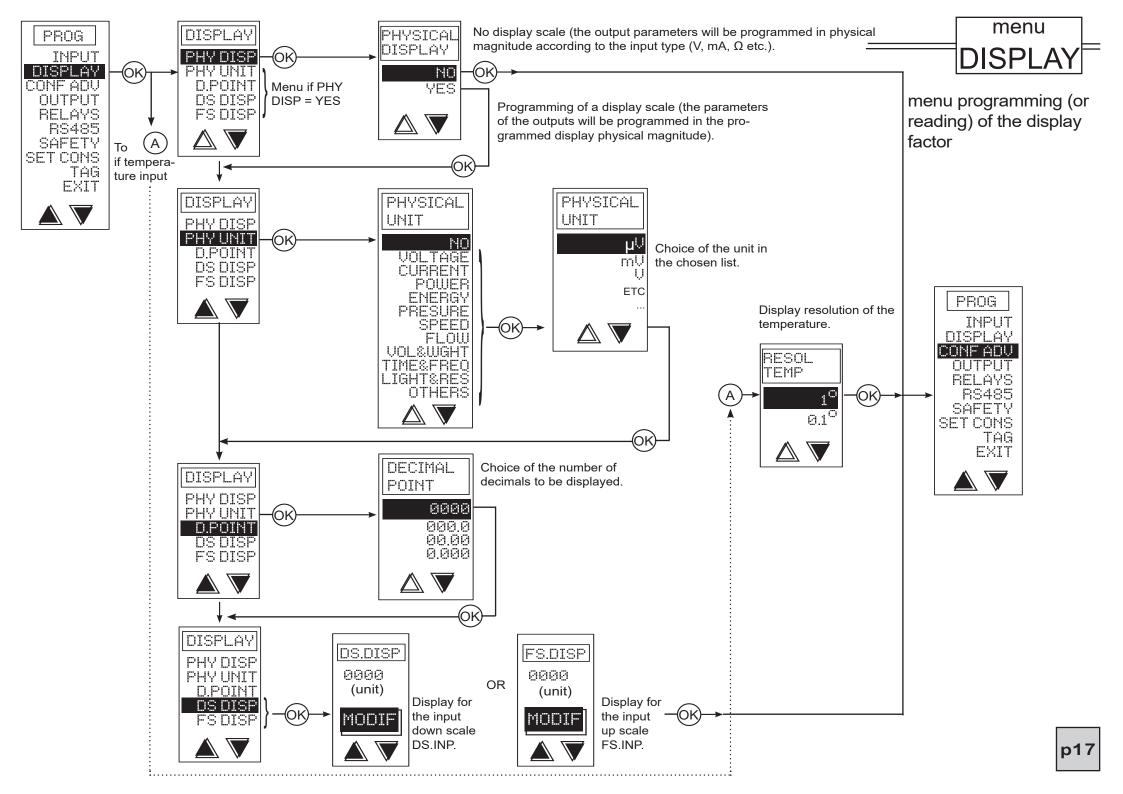


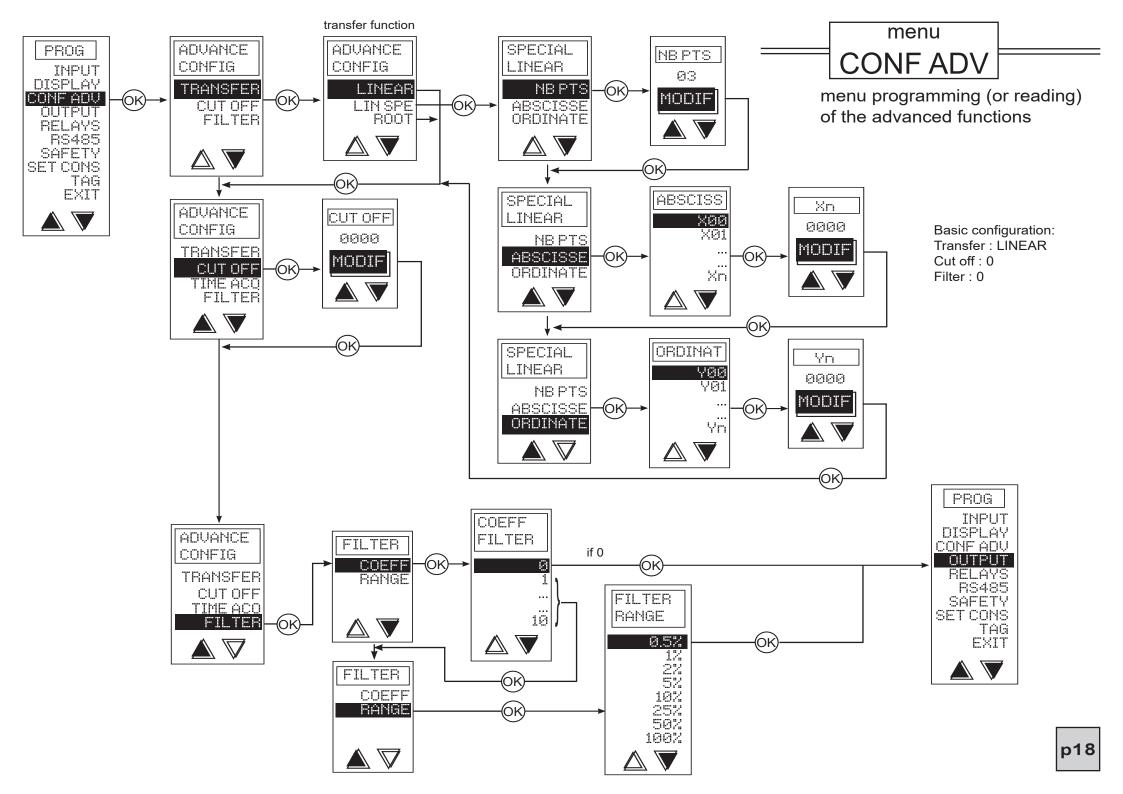












#### **TRANSFER**

LINEAR: Linear function

ROOT: extraction of the square root

 $\sqrt{}$  of the measure brought back in % of the programmed measure range.

Eg.: Input 4-20mA => 12mA gives 0.707 ( $\sqrt{0}$ ,5)

The function square root tends to amplify the input signal background noise

when getting near zero.

To avoid the ripples caused by this noise, simply programme a cut-off value.

LINSPE: Special linearisation

# **Special linearisations:**

For specific applications such as the measurement of volumes, the converter can memorise an unlinear curve programmable in X and in Y.

The curve resulting from your equation can be replaced by a series of linear segments with a maximum of 20 points (19 segments).

Note:

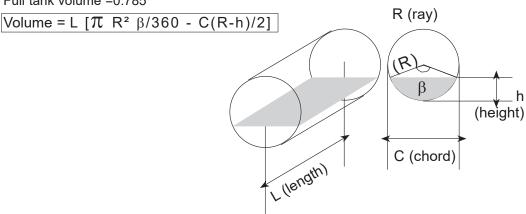
The values of the abscisses (x) must go increasing: value of X00 < value of X01...

#### Example:

For a layed cyclindric tank, 1 meter high (h) and 1 meter long (l); a 0-20 mA linear sensor measures the height of the liquid surface line:

0 meter -> 0 mA (empty tank) 1 meter -> 20 mA (full tank) with cos  $\beta/2$  = (R-h)/R and sin  $\beta/2$  = C/2R Empty tank volume = 0.000

Full tank volume =0.785



Say a curve of 10 equally long segments:

Measure range / number of segments = 20 mA/10 = 2 mA length of the segment.

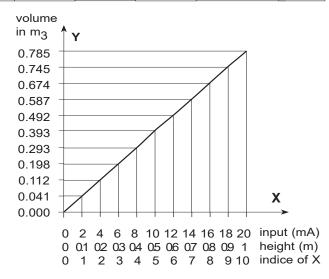
For 10 segments nb = 11 (number of linearisation points).

Input	mA	Height m	Angle Degree	Chord m	Volume m <sup>3</sup>		Outputs in mA
X00	0	0.0	0.00	0.00	Y00	0.000	00.00
X01	2	0.1	73.74	0.60	Y01	0.041	01.04
X02	4	0.2	106.26	0.80	Y02	0.112	02.85
X03	6	0.3	132.84	0.92	Y03	0.198	05.04
X04	8	0.4	156.93	0.98	Y04	0.293	07.47
X05	10	0.5	180.00	1.00	Y05	0.393	10.00
X06	12	0.6	203.07	0.98	Y06	0.492	12.54
X07	14	0.7	227.16	0.92	Y07	0.587	14.96
X08	16	0.8	253.74	0.70	Y08	0.674	17.17
X09	18	0.9	286.76	0.60	Y09	0.745	18.98
X10	20	1.0	360.00	0.00	Y10	0.785	20.00

Programming:
X00 = 0  mA
X10 = 20  mA
nb = 11
$Y00 = 0,000 \text{ m}^3$
$Y10 = 0.785 \text{ m}^3$

Programming from X00 to X10 and from Y00 to Y10 according to the table.

p19



# **CUT OFF**: Programming of the Cut Off value

- If the display up scale > display down scale and if the display is ≤ to the cut off value then it will be held at the down scale.
- If the display up scale < display down scale and if the display is ≥ to the cut off value then it will be held at the down scale.

#### **FILTER**

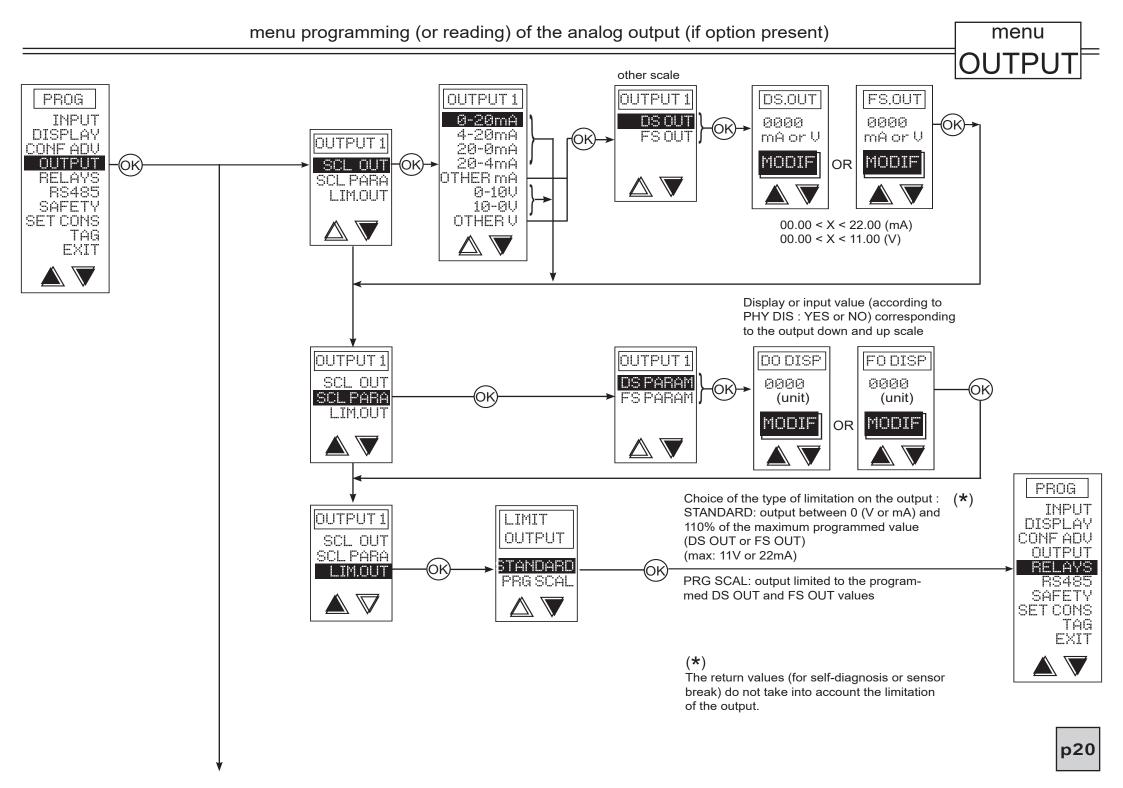
COEFF: integration indice of the digital filtering

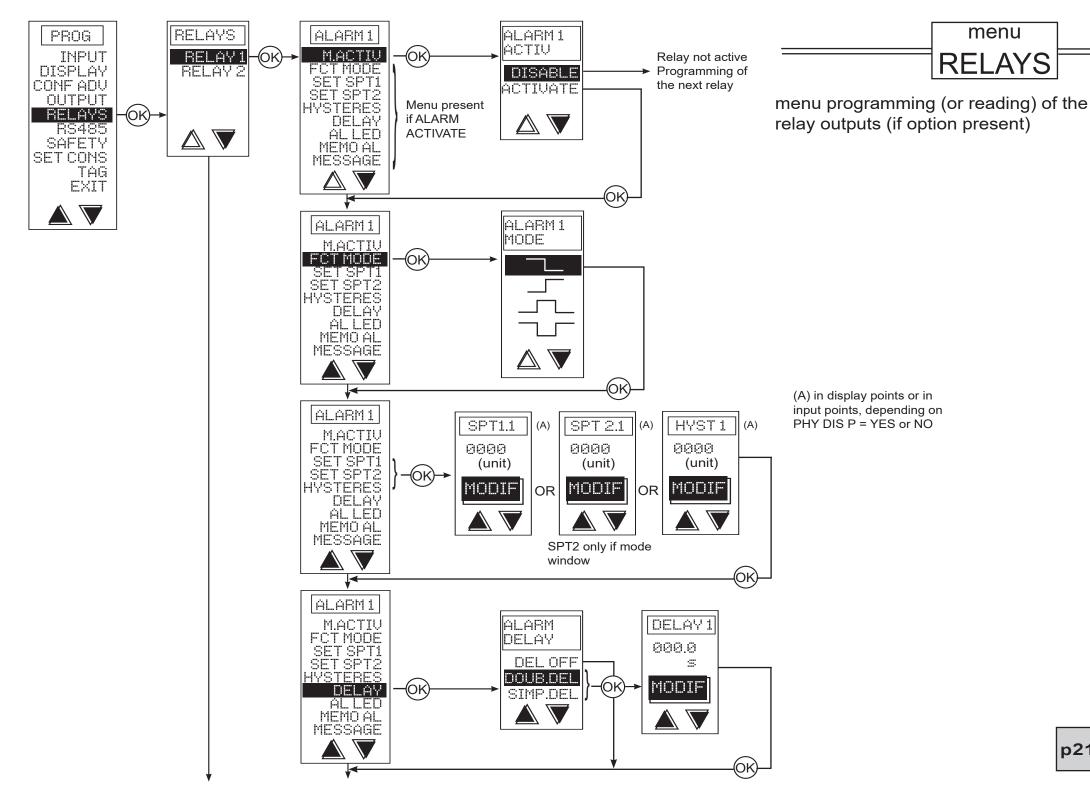
Programmable from 0 to 10, for use in case of unsteady input

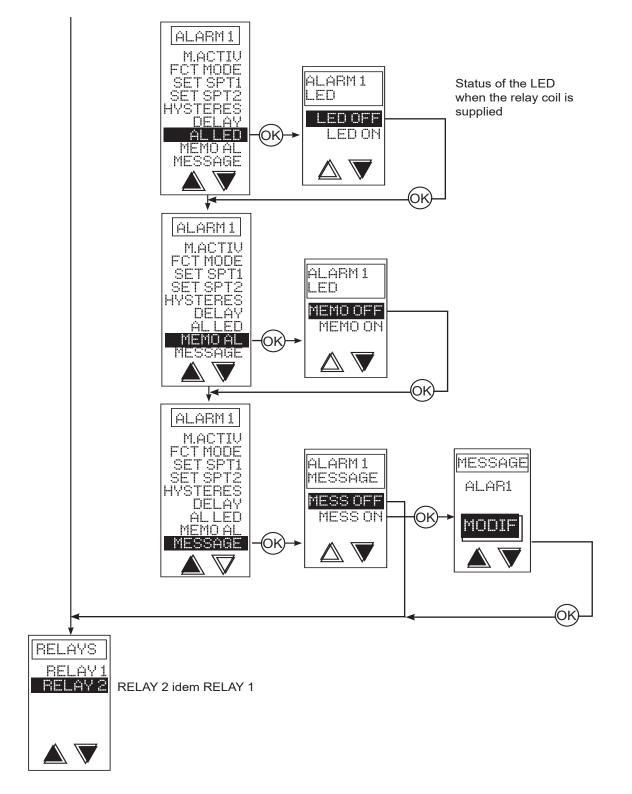
RANGE: Percents of variation of the measure on which the filter will be active

<u>Eg.</u>: COEFF: 3 RANGE: 0.5%

The filter with indice 3 is active when the measure varies by  $\pm$  0,5% When it exceeds 0.5% it will no longer be filtered. This allows to obtain a minimum response time, while eliminating any parasite noise of  $\pm$  0.5% superimposed to the signal, rendering the measure unsteady. If RANGE = 100% the filter will then be active on the whole measure range.

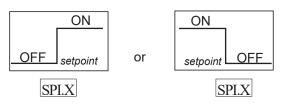








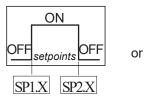
# Mode setpoint

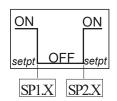


#### Legend:

ON coil supplied OFF coil not supplied

# Mode window

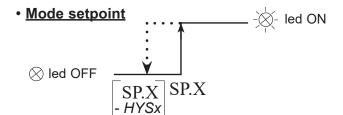


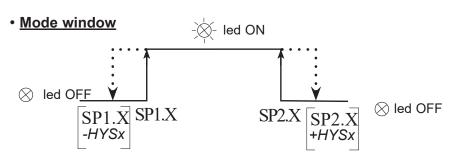


# HYSTx

#### Setting of the hysteresis

The hysteresis is activated on switching from led ON to led OFF; that is to say on switching out of alarm, since the led represents the alarm status.





# DHAYx

# • Time delay on the alarm

Setting of the delay from 0 to 999,9 sec.

DOUB DEL: delay on switching on alarm and off alarm

SIMP DEL: delay only on switching on alarm



 Choice of the status of the relay associated led when the relay coil is supplied



#### Alarm recording

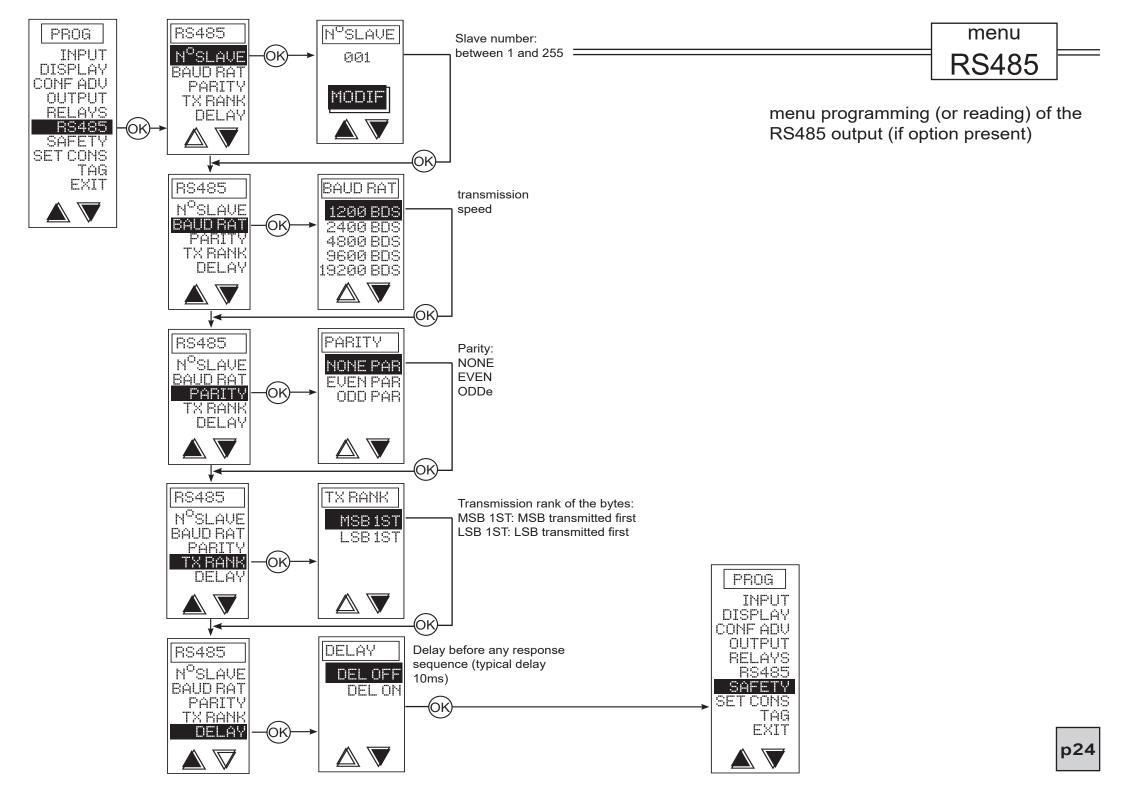
Allows the recording of the alarm after a setpoint has been passed. When the measure reverts below the alarm setpoint, the relay remains ON and the led blinks to warn the user that the setpoint has been passed (to set the alarm recordings to 0 see the menu in the direct functions).

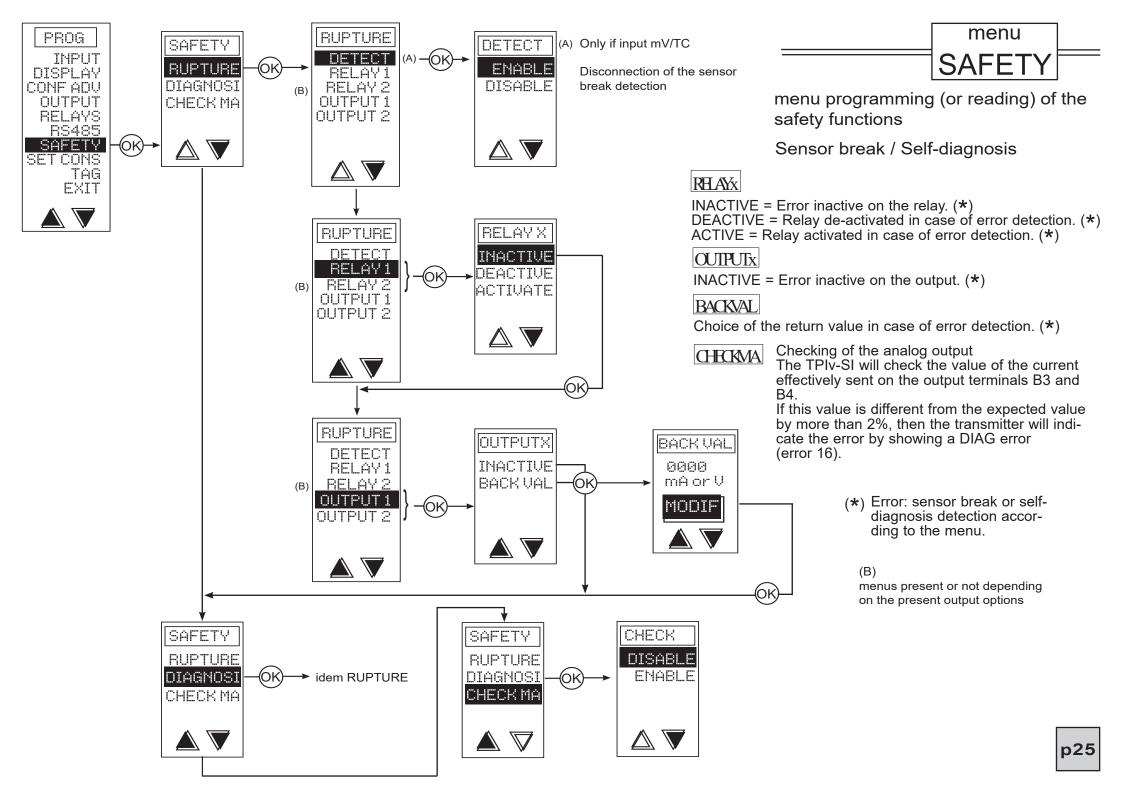
<u>Note</u>: An exit from the mode programming with saving of the configuration will reset the alarm recordings to 0.



# · Display of the alarm messages

A programmed alarm message can be made to appear alternating with the measure. The message will appear only during the alarm that is to say while the associated led is lit.





SAFETIES: SAFETY

### Sensor break

The sensor break can be detected on the inputs mV, Tc, Pt100, Ni100, resistance ( $<400\Omega$ ) and current if the down and up scale <3.5mA.

On the µconsole: the message OPEN appears
On the converter: The LED ON blinks (approx. 4Hz)

<u>Disconnection of the sensor break detection</u>: (if input mV or temperature)

The sensor break detection can be disconnected in order not to disturb some calibrators which may be sensitive to the rupture detection current.

#### Self-diagnosis

The converter permanently watches any drifts of its components. The self-diagnosis serves to warn the user in case of abnormal increase of these drifts before they may provoque false measures.

The self-diagnosis error information can be reported:

· On the display: An error message appears alternating with the measure.

Coding:

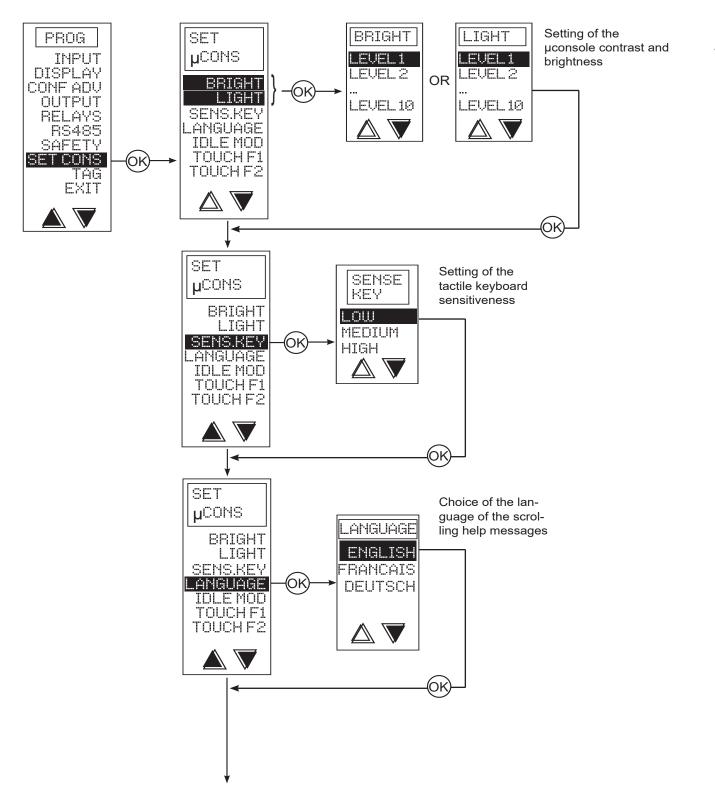
- 1 : Programming error (incoherent programming parameter) (E.PROG)
- 4 : Error on internal offset (excessive drift) (E.OFFS)
- 8 : Calibration error (E.CAL)
- 16 : Checking error of the value of the current sent on the analog output (E.OUT).
  - This error appears systematically if the connector of the analog output (terminal B) is disconnected or if the current output loop is open (with a current different from zero).
- 32 : Error on the CJC (excessive drift or incoherence between the presence or not of the specific terminal «B1CSF-4» and the programming of «CJC» (INT or CON)) (E.CSF)
- 64 : Upper or lower electrical overstepping of the input. (E.OVRG)

If the instrument detects for instance an offset error (4) and a programming error (1) the value of the error code will be 5 (4+1).

Press the screen in mode measure to access the display of the details of the latched self-diagnosis errors.

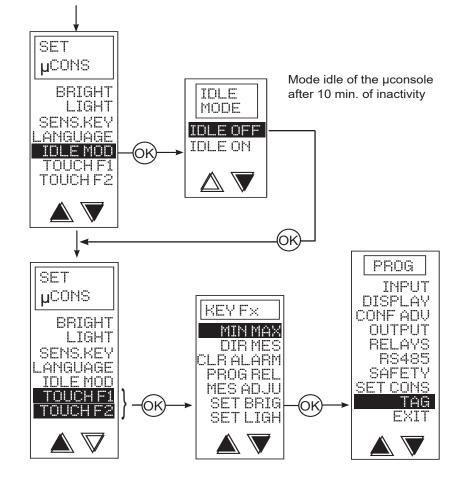
· On the converter:

The LED ON blinks (approx. 4Hz)



menu SET CONS

menu programming (or reading) of the functions concerning the µconsole





Choice of the functions associated with the direct access keys on the measure screen:

F1: left hand key F2: right hand key

MIN MAX: Display and 0 reset of the recorded min. and max.

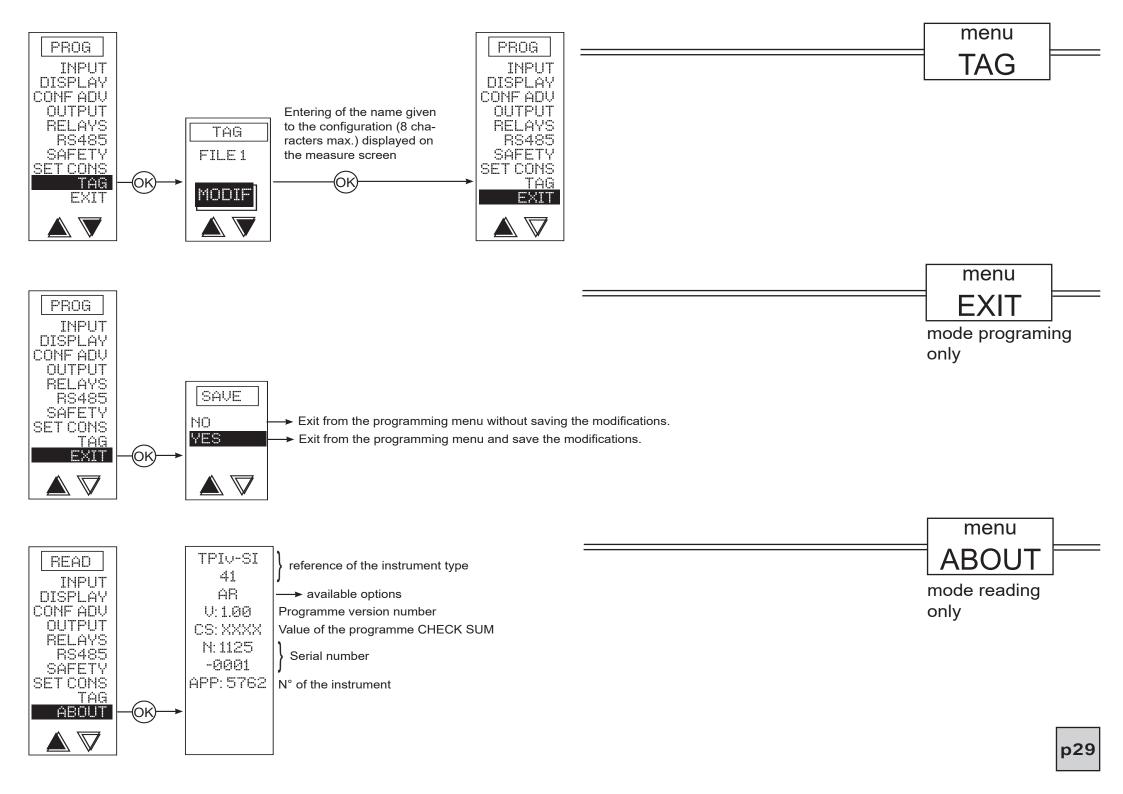
DIR MES: Direct measure of the sensor.

CLR ALARM: 0 reset of the alarm recordings.

PROG REL: Direct setting of the alarm setpoints.

MES ADJU: Access to the adjusting of the input scale.

SET BRIG: Setting of the contrast.
SET LIGH: Setting of the brightness.



# **5. ERROR MESSAGES**

2000 Measure in overrange	Upper or lower electrical overstepping of the input
OPEN Sensor break	OL Displayable value overload
ERR1 Value set out of range	ERxx Self-diagnosis error (see p26)

# 5.1 Blinking of the led ON:

Fast blinking (approx. 4 Hz):
Self-diagnosis active (display ERxx) OR
Sensor break detected (display OPEN) OR
Upper or lower electrical input overstepping (display + ER.64 )
Slow blinking (1 Hz):
The converter is blocked in mode SIMU or GENE

# **6. GENERAL WARRANTY TERMS**

# **WARRANTY** applying and duration

This instrument is under warranty for a duration of 1 year against any design or manufacturing defects, under normal operating conditions.

**Processing conditions** \*: The processing not under warranty will be submitted to the acceptance of a repair estimate. The customer will return the products at his charge, and they will be restored to him after processing. Without a written agreement on the repair estimate within 30 days, the products will not be held.

# 7. ANNEXE: MODBUS

#### 7.1 Table of the Modbus addresses

Word address	<u>Description</u>
0	Measure of the sensor primary
1	decimal point/unit
2	final measure
3	decimal point/unit
4	final measure min.
5	decimal point/unit
6	final measure max.
7	decimal point/unit
12	value of analog output n°1
13	decimal point/unit
14	value of analog output n°2
15	decimal point/unit
51	Self-diagnosis
100	Status relays 1 and 2

#### Measures

The following parameters: measure of the sensor primary, final measure, final measure min. and max. and the values of the analog outputs are transmitted as a module and a unit associated with a position of the decimal point.

# Eg.:

Word address	Decimal value	Coding
0	10 094	module
1	12 289	dec. point / unit

# Coding of the integer point/ unit

H L
BYTE BYTE
point unit: code of correspondance in the list hereunder

### Value of the quartet:

0 : no decimal
16 : 1 decimal
1 : V
32 : 2 decimals
2 : kV
48 : 3 decimals
Eg.: 12 289 = 48 X 256 + 1
The integer encodes the unit V with 3 decimals
The measure read is thus 10.094 V

upper quartet of the byte H

number of decimals

<sup>\*</sup> Complete warranty terms and details available on request.

#### Table of units

Code	Unit
000	
001	V
002	KV
003	Α
004	KA
005	W
006	KW
007	MW
008	GW
009	VAr
010	KVAR
011	MVAR
012	GVAR
013	VA
014	KVA
015	MVA
016	GVA
017	Wh
018	KWh
019	MWh
020	GWh
021	VARh
022	KVARh

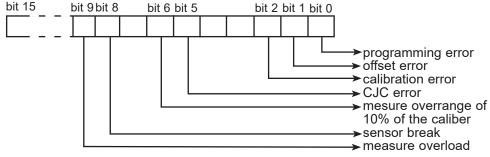
Unit
MVARh
GVARh
Hz
Khz
Deg
Ohms
Kohms
h
mn
s
%
cos PHI
to 099 free

Code	Unit
100	°C
101	°F
103	mm
104	cm
105	m
106	km
107	mBar
108	Bar
109	Pa
110	Kpa
111	Kg/cm2
112	PSI
113	mCE
114	l/s
115	l/mn
116	l/h
117	m3/s
118	m3/mn
119	m3/h
120	tr/s

Code	Unit
122	mm/s
123	cm/s
124	m/s
125	m/mn
126	m/h
127	mm3
128	cm3
129	m3
130	g
131	kg
132	t
133	I
134	hl
135	Rpm
136	CP/mn
137	PH
138	mV AC
139	V AC
140	KV AC
141	mA AC
142	AAC
143	KAAC

Code	Unit
144	mV DC
145	V DC
146	KV DC
147	mA DC
148	A DC
149	KA DC
152	Mohms
153	US.gal/s
154	US.gal/min
155	US.gal/h
156	US.gal
157	lb
158	С
159	imp
160	CP
161	mA
163	mA.h
164	A.h
165	μV
166	mV

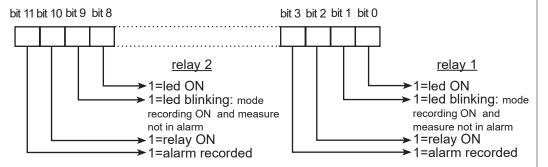
# Integer selfdiagnosis: (address 51)



121 rad/s

(eg.: 15V measure on a 10V caliber)

# Integer status of relays 1 and 2: (address 100)



# 7.2 Description of the born Modbus functions:

# Reading of N words: Function n°3

# Request sequence:

Clavia	Function	1st word	address	Nbr of	words	
Slave number	Function 3 or 4					CRC 16
		MSB	LSB	MSB	LSB	
1 byte	1 byte	<b>←</b> 2 b	ytes	≥< 2 b	ytes →	2 bytes

### Response sequence:

Slave	Function		1st word	value	2nd word	value	000.40
number	3 or 4	of read bytes	MSB	LSB	MSB	LSB	CRC 16
1 byte	1 byte	1 byte	<b>←</b> 2 by	ytes	- <b>←</b> 2 by	ytes →	2 bytes

# Writing of N words: Function N°16:

#### Request sequence:

Slave number	Function 16	1st word address	Numbr of words to be enfor.	Numbr of bytes to be enfor.	Value of the words to be enforced	CRC 16
1 byte					← n bvtes →	

### Response sequence:

Slave number	Function 16	1st word address	Numbr of words to be enfor.	CRC 16
1 byte	1 byte		2 bytes	

# Writing of 1 word: Function N°6:

# Request sequence:

Slave number	Function 6	Word address	Value of the word to be enf.	CRC 16
1 byte	1 byte	2 bytes	2 bytes	2 bytes

#### Response sequence:

|--|

1 byte 1 byte 2 bytes 2 bytes 2 bytes

#### Exception pattern:

Slave number	Function reques- ted with MSB=1	Error code	CRC 16
1 byte	1 byte	1 byte	2 bytes

Values of the error codes:

1: Function code unknown

2: Address incorrect

3: Data incorrect

9: Writing impossible

# 7.3 Reading in double integer format:

Example: Reading of the displayed measure

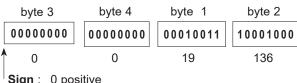
# Request:

254	03	0	2	0	2	CRC 16
Slave number	Reading of n words	Add	ress	Number	of words	

# • Response with a positive measure:



# Value of the measure:

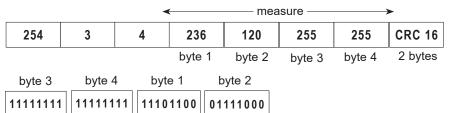


Sign: 0 positive 1 negative

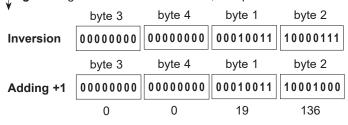
Measure = byte 3 x 
$$256^3$$
 + byte 4 x  $256^2$  + byte 1 x  $256$  + byte 2  
= 0 x  $256^3$  + 0 x  $256^2$  + 19 x  $256$  + 136  
= 5000

Reading of the address 3 => decimal point = 2 => displayed measure 50.00

# • Response with a negative measure:



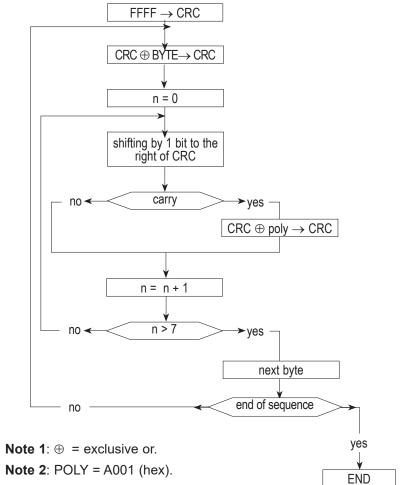
**Sign**: 1 negative: inversion of the bits, and plus 1.



Measure = -(byte 3 x 
$$256^3$$
 + byte 4 x  $256^2$  + byte 1 x  $256$  + byte 2)  
= -(0 x  $256^3$  + 0 x  $256^2$  + 19 x  $256$  + 136)  
= -5000

Reading of address 3 => decimal point = 2 => displayed measure -50.00

# 7.4 CRC 16 calculation algorythm:



**Note 1**:  $\oplus$  = exclusive or.

#### Note 3:

The CRC16 calculation applies to all bytes in the sequence (except CRC16).

Caution! In the CRC 16, the 1st sent byte is the LSB.

*Example*: Sequence 1-3-0-75-0-2 CRC16 = 180-29 (the values are decimal).